

**3. Ball bearing tolerances**

**3.1 Standard of tolerances**

Ball bearing "tolerances" or dimensional accuracy and running accuracy, are regulated by ISO and JIS standards (rolling bearing tolerances). For dimensional accuracy, these standards prescribe the tolerances necessary when installing bearings on shafts or in housings. Running accuracy is defined as the allowable limits for bearing runout during operation.

Table 3.1 Comparison of tolerance classifications of national standards

Standard		Tolerance class				
Japanese industrial standard (JIS)	JIS	class 0,6X	class 6	class 5	class 4	class 2
International Organization for Standardization (ISO)	ISO	Normal class Class 6X	Class 6	Class 5	Class 4	Class 2
Deutsches Institut für Normung (ISO)	DIN	P0	P6	P5	P4	P2
American National Standards Institute (ANSI)	ANSI/ABMA	ABEC-1	ABEC-3	ABEC-5	ABEC-7	ABEC-9

**3.2 Tolerances for radial bearings**

Table 3.2 Inner rings

(Unit:  $\mu\text{m}$ )

Nominal bore diameter $d$ mm	Single plane mean bore diameter deviation $\Delta d_{mp}$	Single radial plane bore diameter variation													
		diameter series 9					maxidiameter series 0.1								
		class 0	class 6	class 5	class 4	class 2	class 0	class 6	class 5	class 4	class 2				
over incl.	high low	high low	high low	high low	high low	0	6	5	4	2	0	6	5	4	2
10 18	0 -8	0 -7	0 -5	0 -4	0 -2.5	10	9	5	4	2.5	8	7	4	3	2.5
18 30	0 -10	0 -8	0 -6	0 -5	0 -2.5	13	10	6	5	2.5	10	8	5	4	2.5
30 50	0 -12	0 -10	0 -8	0 -6	0 -2.5	15	13	8	6	2.5	12	10	6	5	2.5
50 80	0 -15	0 -12	0 -9	0 -7	0 -4.0	19	15	9	7	4.0	19	15	7	5	4.0
80 120	0 -20	0 -15	0 -10	0 -8	0 -5.0	25	19	10	8	5.0	25	19	8	6	5.0

Table 3.3 Inner rings

Nominal bore diameter $d$ mm	Single radial plane bore diameter variation $V_{dp}$ maxidiameter series 2,3,4	Mean single plane bore diameter variation $V_{dmp}$					Inner ring radial runout $K_{in}$					Face runout with bore $S_d$		
		class 0	class 6	class 5	class 4	class 2	class 0	class 6	class 5	class 4	class 2	class 5	class 4	class 2
		over incl.	max.	max.	max.	max.	max.	max.	max.	max.	max.	max.	max.	max.
10 18	6 5 4 3 2.5	6 5 3 2.0 1.5	10 7 4 2.5 1.5	7.0 3.0 1.5										
18 30	8 6 5 4 2.5	8 6 3 2.5 1.5	13 8 4 3.0 2.5	8.0 4.0 1.5										
30 50	9 8 6 5 2.5	9 8 4 3.0 1.5	15 10 5 4.0 2.5	8.0 4.0 1.5										
50 80	11 9 7 5 4.0	11 9 5 3.5 2.0	20 10 5 4.0 2.5	8.0 5.0 1.5										
80 120	15 11 8 6 5.0	15 11 5 4.0 2.5	25 13 6 5.0 2.5	9.0 5.0 2.5										

Table 3.4 Inner rings

Nominal bore diameter <i>d</i>		Inner ring axial runout (with side) <i>S<sub>ra</sub></i> <sup>Ⓢ</sup>			Inner ring width deviation $\Delta B_s$								Inner ring width variation <i>VB<sub>s</sub></i>						
mm		class 5	class 4	class 2	normal				modified <sup>Ⓢ</sup>				<i>VB<sub>s</sub></i>						
over	incl.	high	low	high	low	high	low	high	low	high	low	high	low	class 0	class 6	class 5	class 4	class 2	
10	18	7	3	1.5	0	-120	0	-80	0	-80	0	-250	0	-250	20	20	5	2.5	1.5
18	30	8	4	2.5	0	-120	0	-120	0	-120	0	-250	0	-250	20	20	5	2.5	1.5
30	50	8	4	2.5	0	-120	0	-120	0	-120	0	-380	0	-250	20	20	5	3.0	1.5
50	80	8	5	2.5	0	-150	0	-150	0	-150	0	-380	0	-250	25	25	6	4.0	1.5
80	120	9	5	2.5	0	-200	0	-200	0	-200	0	-380	0	-380	25	25	7	4.0	2.5

Note: ① The dimensional difference  $\Delta d$  of bore diameter to applied for class 4 and 2 is the same as the tolerance of dimensional difference  $\Delta d_{mp}$  of average bore diameter. However, the dimensional difference is applied to diameter series 0, 1, 2, 3 and 4 against Class 4, and to all the diameter series against Class 2.  
 ② To be applied for deep groove ball bearing and angular contact ball bearings.  
 ③ To be applied for individual raceway rings manufactured for combined bearing use.

Table 3.5 Outerrings

(Unit:  $\mu\text{m}$ )

Nominal Outside diameter <i>D</i>		Single plane mean outside diameter deviation $\Delta D_{mp}$							Single radial plane outside diameter variation <i>VD<sub>p</sub></i>												
mm		class 0		class 6		class 5		class 4 <sup>Ⓢ</sup>		class 2 <sup>Ⓢ</sup>		diameter series 9					max diameter series 0,1				
over	incl.	high	low	high	low	high	low	high	low	high	low	class 0	class 6	class 5	class 4	class 2	class 0	class 6	class 5	class 4	class 2
6	18	0	-8	0	-7	0	-5	0	-4	0	-2.5	10	9	5	4	2.5	8	7	4	3	2.5
18	30	0	-9	0	-8	0	-6	0	-5	0	-4.0	12	10	6	5	4.0	9	8	5	4	4.0
30	50	0	-11	0	-9	0	-7	0	-6	0	-4.0	14	11	7	6	4.0	11	9	5	5	4.0
50	80	0	-13	0	-11	0	-9	0	-7	0	-4.0	16	14	9	7	4.0	13	11	7	5	4.0
80	120	0	-15	0	-13	0	-10	0	-8	0	-5.0	19	16	10	8	5.0	19	16	8	6	5.0
120	150	0	-18	0	-15	0	-11	0	-9	0	-5.0	23	19	11	9	5.0	23	19	8	7	5.0
150	180	0	-25	0	-18	0	-13	0	-10	0	-7.0	31	23	13	10	7.0	31	23	10	8	7.0
180	250	0	-30	0	-20	0	-15	0	-11	0	-8.0	38	25	15	11	8.0	38	25	11	8	8.0

Table 3.6 Outerrings

Nominal Outside diameter <i>D</i>		Single radial plane outside diameter variation <i>VD<sub>p</sub></i>					Single radial plane outside diameter variation <i>VD<sub>p</sub></i> <sup>Ⓢ</sup>		Mean single plane outside diameter variation <i>VD<sub>mp</sub></i>				
mm		max diameter series 2,3,4					capped bearings diameter series 2,3,4		<i>VD<sub>mp</sub></i>				
over	incl.	class 0	class 6	class 5	class 4	class 2	class 0	max.	class 0	class 6	class 5	class 4	class 2
6	18	6	5	4	3	2.5	10	9	6	5	3	2.0	1.5
18	30	7	6	5	4	4.0	12	10	7	6	3	2.5	2.0
30	50	8	7	5	5	4.0	16	13	8	7	4	3.0	2.0
50	80	10	8	7	5	4.0	20	16	10	8	5	3.5	2.0
80	120	11	10	8	6	5.0	26	20	11	10	5	4.0	2.5
120	150	14	11	8	7	5.0	30	25	14	11	6	5.0	2.5
150	180	19	14	10	8	7.0	38	30	19	14	7	5.0	3.5
180	250	23	15	11	8	8.0	—	—	23	15	8	6.0	4.0

Table 3.7 Outer rings

Nominal Outside diameter D mm	Outer ring radial runout K <sub>en</sub>					Outside surface inclination SD			Outside ring axial runout S <sub>en</sub> <sup>Ⓢ</sup>			Outer ring width deviation Δ <sub>cs</sub>	Outer ring width variation V <sub>cs</sub>				
	over	incl.	class	class	class	class	class	class	class	class	class		class 0,6	class 5	class 4 max.	class 2	
			0	6	5 max.	4	2	5	4 max.	2	5						4 max.
6	18	15	8	5	3	1.5	8	4	1.5	8	5	1.5	Identical to ΔB <sub>s</sub> of inner ring of same bearing	Identical to ΔB <sub>s</sub> and V <sub>is</sub> of inner ring of same bearing	5	2.5	1.5
18	30	15	9	6	4	2.5	8	4	1.5	8	5	2.5			5	2.5	1.5
30	50	20	10	7	5	2.5	8	4	1.5	8	5	2.5			5	2.5	1.5
50	80	25	13	8	5	4.0	8	4	1.5	10	5	4.0			6	3.0	1.5
80	120	35	18	10	6	5.0	9	5	2.5	11	6	5.0			8	4.0	2.5
120	150	40	20	11	7	5.0	10	5	2.5	13	7	5.0			8	5.0	2.5
150	180	45	23	13	8	5.0	10	5	2.5	14	8	5.0			8	5.0	2.5
180	250	50	25	15	10	7.0	11	7	4.0	15	10	7.0			10	7.0	4.0

- Note: Ⓢ The dimensional difference ΔD<sub>s</sub> of outer diameter to be applied for classes 4 and 2 is the same as the tolerance of dimensional difference ΔD<sub>mp</sub> of average outer diameter. However, the dimensional difference is applied to diameter series 0,1,2,3 and 4 against Class 4, and also to all the diameter series against Class 2.
- Ⓢ To be applied in case snap rings are not installed on the bearings.
  - Ⓢ To be applied for Deep Groove Ball Bearings and Angular Contact Ball Bearings.

**4 Bearing fits**

**4.1 Interference**

For rolling bearings, inner and outer rings are fixed on the shaft or in the housing so that relative movement does not occur between fitted surfaces during operation or under load. This relative movement (referred to as "creep") between the fitted surfaces of the bearing and the shaft or housing can occur in a radial direction, an axial direction, or in the direction of rotation. To help prevent this creeping movement, bearing rings and the shaft or housing are installed with one of three interference fits, a "tight fit" (also called shrink fit), "transition fit" or "loose fit" (also called clearance fit), and the degree of interference between their fitted surfaces varies.

The most effective way to fix the fitted surfaces between a bearing's raceway and shaft or housing is to apply a "tight fit." The advantage of this tight fit for thin walled bearings is that it provides uniform load support over the entire ring circumference without any loss of load carrying capacity. However, with a tight fit, ease of installation and disassembly is lost. And when using a non-separable bearing as the floating-side bearing, axial displacement is not possible. For this reason, a tight fit cannot be recommended in all cases.

**4.2 The necessity of a proper fit**

In some cases, improper fit may lead to damage and shorten bearing life, therefore it is necessary to make a careful analysis in selecting a proper fit. Some of the negative conditions caused by improper fit are listed below.

- Raceway cracking, early peeling and displacement of raceway
- Raceway and shaft or housing abrasion caused by creeping and fretting corrosion
- Seizing caused by loss of internal clearances
- Increased noise and lowered rotational accuracy due to raceway groove deformation